

BEYOND THE POSSIBLE

unmanned aerial systems for professionals

















Peter Henning CEO and Remote Pilot



Jochen Anglett
CTO and Developer

WHO WE ARE

a team of inspired professionals

Vectorbirds airborne systems has started in 2019, to fill a gap in the field of professional UAVs for authorities and organizations with security tasks.

It is our passion, to design and manufacture reliable, innovative and sustainable UAV systems.

Every single System is meticulously handcrafted in Germany.

Our tactical multicopters and helicopters are deployed by military, special forces and security, rescue forces and fire departments, as well as in agriculture, research and industry. Vectorbirds airborne systems ist 2019 angetreten, eine Lücke im Bereich der professionellen UAVs für Behörden und Organisationen mit Sicherheitsaufgaben zu schließen.

Die Entwicklung und Fertigung von zuverlässi gen, innovativen und nachhaltigen UAV-Systemen ist unsere Passion.

Jedes einzelne System wird von uns in sorgfältigster Handarbeit in Deutschland gefertigt.

Unsere taktischen Multikopter und Helikopter kommen bei Militär- und Spezialeinheiten, Sicherheits- und Rettungskräften, Feuerwehren sowie in der Landwirtschaft, Forschung und Industrie zum Einsatz.





9 ENERGY INDUSTRY

SURVEYING AND CARTOGRAPHY

SCIENCE AND RESEARCH

AGRICULTURE AND FORESTRY

CONSTRUCTION AND FACILITY MANAGEMENT

FILM AND PHOTOGRAPHY

ANIMAL AND ENVIRONMENTAL PROTECTION



Kite75



F E A T U R E S



AUTOPILOT

- GPS mode, fly like on rails even under windy conditions
- Autonomous start and landing
- Autonomous return to launch
- Autonomous mission by waypoints
- Camera trigger on predefined GPS positions
- Point of Interest (circling around a defined GPS coordinate point)
- Care-Free Mode (UAV always moves in relation to the pilot)
- Follow-Mode (UAV follows the GPS coordinates of a moving person or vehicle
- LIDAR with 320° obstacle avoidance
- Additional features according to requirements and use cases

COMPANION COMPUTER

- Camera control, real-time image evaluation and display
- Pilot cam control, real-time image analysis and display
- Autopilot data HUD
- **♦** Multi-core CPU, AI application ready

CAMERA CONTROL

- 90° rotatable pilot HD camera
- Mode switching: Still, Movie and Image Stabilization
- Ozoom (10x 30x optical)
- Further camera settings possible according to requirements and use case

FLIGHT PLATFORM

- Downward folding quick-click arms for easy transport and fast readiness for use
- Retractable landing gear for undisturbed 360° round vision
- Practical handhold with integrated flight data sensors
- Battery rail system, automatically connected at click
- Gimbal quick exchange system with hotplug function
- Camera quick exchange system
- Electronic decoupling of both batteries

CONTROLLER

• Various controllers available for different application scenarios

Kite75





| Dimensions | Rotoraxis diameter: Package size: Ready to fly: | 950 mm Ø 430 mm x 430 mm x 580 mm 650 mm x 650 mm x 580 mm |
|-----------------------------|---|--|
| Propellers | 52cm Ø | |
| Motors | Brushless Motors | |
| Batteries | 2x Lithium-Ion Batteri | es, redundant system |
| Weight | 3400 g | |
| Max. Take-off weight | 12000 g | |
| Speed | 70 km/h max | |
| Climbing performance | 4 m/s max. | |
| Flight altitude ASL | 4000m max. | |
| Windresistance | 15m/s max. | |
| Operating temperature range | -20°C to +50°C | |
| Protection class | IP54 | |
| Flight time | 42 Min. with Litium-Io | n-Batteries |
| Sensors | 2x Magnetometer, 2x (heated IMU, 320° LIDA | |
| Frequencies | 2,4 GHz or 868 Mhz control link 2,4 Ghz or 5,8 GHz digital video transmission other frequencies on request! | |
| Operating range | 10 km max. | |
| Data transmission/protocols | AES 256 encryption, Months optional STANAG 4586 | |
| Video standards | MPEG-2, MISB ST 0601 | / KLV Metadata |





F ENERGY INDUSTRY

SCIENCE AND RESEARCH

AGRICULTURE AND FORESTRY

CONSTRUCTION AND FACILITY MANAGEMENT

ANIMAL AND ENVIRONMENTAL PROTECTION





GRABBITG6



F E A T U R E S



AUTOPILOT

- ◆ GPS mode, fly like on rails even under windy conditions
- Autonomous start and landing
- Autonomous return to launch
- Autonomous missions by waypoints
- Camera trigger on predefined GPS positions
- Point of Interest (circling around a defined GPS coordinate point)
- Care-Free Mode (UAV always moves in relation to the pilot)
- Follow-Mode (UAV follows the GPS coordinates of a moving person or vehicle
- Additional features according to requirements and use cases
- Front LIDAR for obstacle detection

COMPANION COMPUTER

- Camera control, real-time image evaluation and display
- Pilot cam control, real-time image analysis and display
- Autopilot data HUD
- **♦** Multi-core CPU, AI application ready

CAMERA CONTROL

- ◆ Mode switching: Still, Movie and Image Stabilization
- Ozoom (10x 30x optical)
- ◆ Object tracking
- Further camera settings possible according to requirements and use case

FLIGHT PLATFORM

- Foldable quick-click arms for easy transport and fast readiness for use
- **●** Exchangeable drive unit
- Exchangeable landing gear
- Practical handhold with integrated flight data sensors
- Battery rail system, quick exchange
- Camera quick exchange system with hotplug function

CONTROLLER

- **♦** Milled Hall-Gimbals
- 7" ultra bright HD Display
- **♦** Linux Operating System
- 20km range
- ♠ AES encryption

GRABBITG6

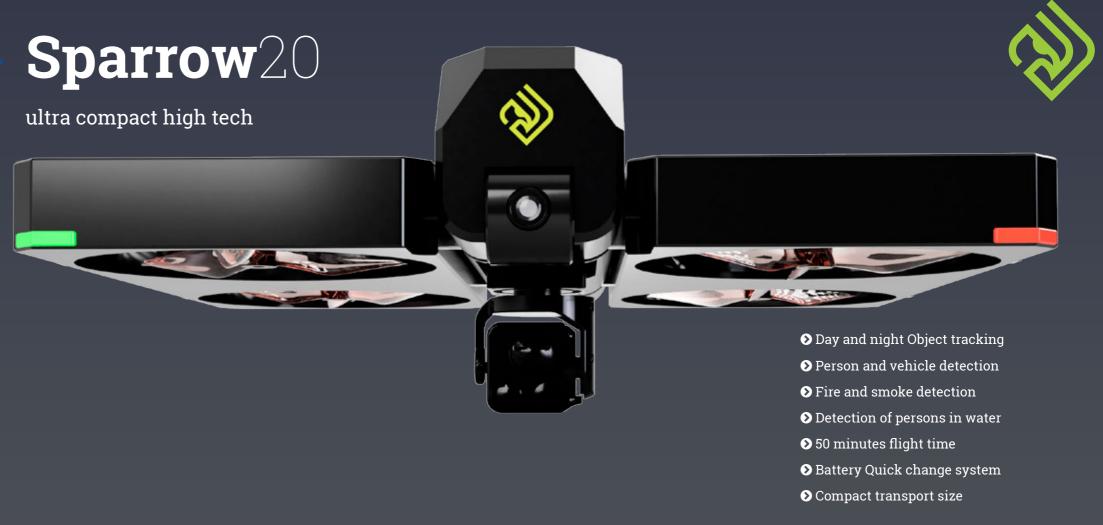


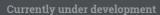


| Dimensions | Rotoraxis diameter: Package size: Ready to fly: | 670 mm Ø 700 mm x 200 mm x 220 mm 540 mm x 540 mm x 270 mm |
|-----------------------------|--|--|
| Propeller | 42cm Ø | |
| Motors | Brushless Motors | |
| Batteries | 1x Lithium-Ion Battery | y |
| Weight | 2700 g | |
| Max. Take-off weight | 3300 g | |
| Speed | 45 km/h max. | |
| Climbing performance | 3,5 m/s max. | |
| Flight altitude ASL | 2500m max. | |
| Wind resistance | 10m/s max. | |
| Operating temperature range | -20°C to +50°C | |
| Protection class | IP54 | |
| Flight time | 60 Min. with Bi-Copte | r-Drive unit |
| Sensors | 2x Magnetometer, 2x 0 heated IMU, distance- | GNSS, 2x Barometer, LIDAR, altitude-LIDAR |
| Frequencies | 2,4 GHz or 868 Mhz Co 2,4 Ghz or 5,8 GHz digi other frequencies on r | ital video transmission |
| Operating range | 10 km max. | |
| Data transmission/protocols | AES 256 encryption, Noptional STANAG 4586 | |
| Video Standards | MPEG-2, MISB ST 060 | 1 / KLV Metadata |



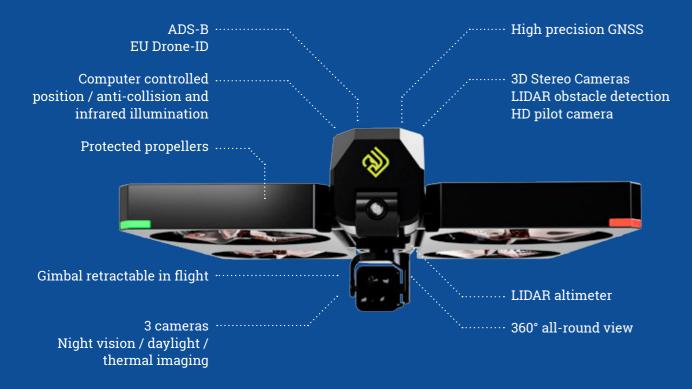
- ***** MARINE RECONNAISSANCE
- INDOORS AND CONFINED SPACES
- SITUATION AWARENESS
- **OBLIND SPOT CLARIFICATION**
- DISMOUNTED SOLDIER APPLICATIONS
- PERSONAL RECONNAISSANCE SYSTEM
- SECRET MISSIONS
- AI APPLICATIONS PLATFORM







SPARROW20



Linux controller with full access to all autopilot and payload functions



FEATURES



AUTOPILOT

- ◆ GPS mode, fly like on rails even under windy conditions
- Autonomous start and landing
- Autonomous return to launch
- Autonomous missions by waypoints
- Camera trigger on predefined GPS positions
- Point of Interest (circling around a defined GPS coordinate point)
- Care-Free Mode (UAV always moves in relation to the pilot)
- ◆ Follow-Mode (UAV follows the GPS coordinates of a moving person or vehicle
- Additional features according to requirements and use cases
- Front LIDAR rangefinder for obstacle detect and avoid

COMPANION COMPUTER

- Payload control, real-time image evaluation and display
- Pilot cam control, real-time image analysis and display
- Precision landings on optical markers
- ROS (Robot Operation System) API
- HUD with raltime autopilot data
- Multi-core CPU, AI application ready

CAMERA / PAYLOAD

- Static and moving object tracking
- KLV Metadata
- ◆ Geo Referencing Point to coordinate, Ground crossing location
- Autonomus SAR functions
- Direct Payload communication

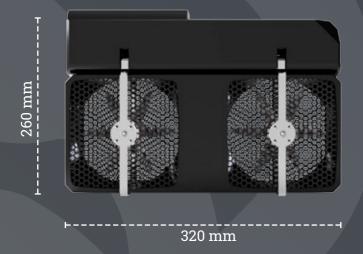
FLIGHT PLATFORM

- Folding quick-click drive unit for easy transport and fast readiness for use
- Automatic gimbal release
- **♦** Battery rail system

CONTROLLER

- Milled hall-gimbals
- 7" ultra bright HD display
- **♦** Linux operating system
- **②** 20km range
- ♠ AES encryption

SPARROW20





60 mm



| Dimensions | Rotoraxis diameter: Package size: Ready to fly: | 290 mm Ø 320 mm x 210 mm x 60 mm 320 mm x 320 mm x 60 mm |
|-----------------------------|---|--|
| Propeller | 177mm Ø | |
| Motors | Brushless motors | |
| Batteries | Lithium Ion | |
| Weight | 900 g | |
| Max. Take-off weight | 900 g | |
| Speed | 50 km/h max. | |
| Climbing performance | 5 m/s max. | |
| Flight altitude ASL | 2500m max. | |
| Wind resistance | 8m/s max. | |
| Operating temperature range | -20°C to 50°C | |
| Protection class | IP54 | |
| Flight time | 50 Min. | |
| Sensors | redundant sensors, 2x 2x GPS, 2x barometer, 3D stereo cameras, Al | heated IMU, |
| Frequencies | 2,4 GHz or 868 Mhz co 2,4 Ghz or 5,8 GHz dig other frequencies on | ital video transmission |
| Operating range | 10 km max. | |
| Data transmission/protocols | AES 256 encryption, Noptional STANAG 458 | |
| Video Standards | MPEG-2, MISB ST 060 | 1 / KLV Metadata |

TELEVATOR

mobile tether UAS port



- centimeter-accuracy
- Take-off and landing from moving vehicle optional
- Suitable for armoured vehicles, pick-ups, trucks and trailers
- ♦ Wired UAS power supply
- ♦ Wide range of climatic conditions
- Fully remote controllable
- ▶ Automatic levelling Platform

TECHNICAL DATA PLATFORM

| Energy supply | 230V, 50Hz | 4,8A |
|---------------------------------|------------------------|------------------------|
| | 24V | 90A |
| | 12V | 180A |
| 230V | DIN EN 50699 VI | E 0702:2021 / VDE 0100 |
| Platform dimensions (H x W x L) | 480mm x 1000mm x 800mm | |
| Weight | 55kg | |
| Cable length | 100m | |
| Power | 1200W | |
| Data transmission / control | TCP/IP 1000BASI | E-T, 200Mbit |

TECHNICAL DATA UAS

| Dimensions | Rotor axis diameter 900 mm Ø 600 mm x 600 mm x 450 mm |
|-------------------------------|--|
| Propellers | 52cm Ø |
| Motors | Brushless Motors |
| Weight | 4500 g |
| Max. Take-off weight | 9000 g |
| Speed | 70 km/h max. |
| Climbing performance | 4 m/s max. |
| Flight altitude ASL | 2500m max. |
| Wind resistance | 15m/s max. |
| Data transmission / protocols | via radio or tether cable, STANAG 4586, MavLink |
| Video Features and Standards | Object tracking, image stabilisation MPEG-2, MISB ST 0601 |

TECHNICAL DATA OVERALL SYSTEM

| Working temperature | -20°C to +55°C |
|---------------------|-----------------------------|
| Protection class | IP54 |
| Humidity | 20% - 90% RH non condensing |





PAYLOAD OPTIONS

maximum fleet flexibility!



Sony 30x Zoom High Definition 30x optical zoom electronic image stabilization video and image capture

FLIR Boson 640x512 Pixel thermal Image 12 color palettes

RGB Camera

High Definition video and image capture

FLIR Lepton 160x120 Pixel thermal Image 12 color palettes

picture in picture

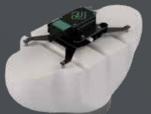
RGB Zoom Camera High Definition

10x optical zoom video and image capture

All camera bodies can also be mounted on **Grabbit**G6

Custom Payload Adapter

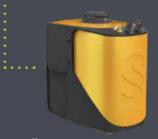




MicaSense Multispectral Cameras



Workswell Thermal Cameras



YellowScan Laser Scanner



Trichogramma dropping device



Sony Alpha 6000 / Alpha 7



LED Headlights

TETHER GROUNDSTATIONS

 ∞ infinite flight time







| Supply voltage | 230V, 50Hz | 230V, 50Hz, 4,8A | |
|-------------------------------|------------|-----------------------|--|
| Dimensions (H x W x D) | 272mm x 5 | 272mm x 591mm x 576mm | |
| Weight | 32kg | | |
| Cable length | 60m | 100m | |
| Power | 1400W | 1200W | |
| Data transmission (optional) | 1000BASE- | T, up to 200Mbit | |
| Remote control (optional) | UART 5V T | TL. | |
| 230V Mains connection | Neutrik® p | owerCON TRUE | |
| Network connection (optional) | Neutrik® e | therCON CAT6A | |
| Remote control (optional) | D-Sub 9 po | le, female | |









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